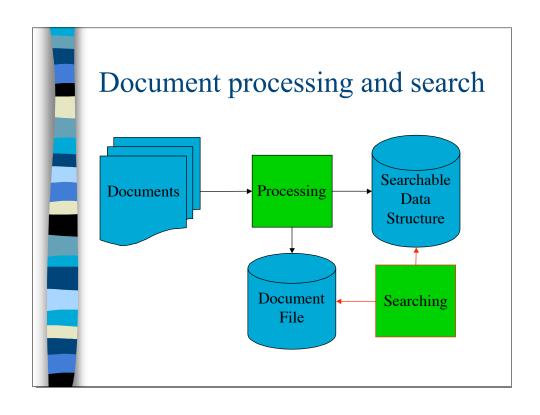
# INFSCI 2140 Information Storage and Retrieval Lecture 7: Data Structures and Algorithms

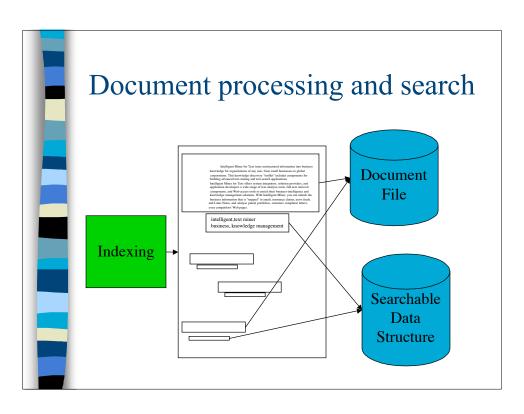
#### Peter Brusilovsky

http://www2.sis.pitt.edu/~peterb/2140-051/

#### Overview

- Document processing, storage, search
- Document files
  - the issue of record length
- Search problem
- Simple search solutions
- Algorithms and complexity
- Advanced searchable data structures



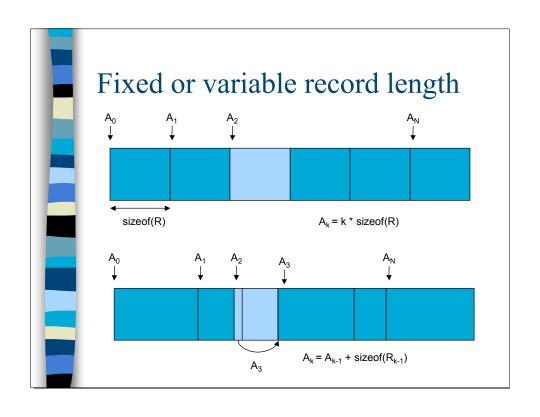


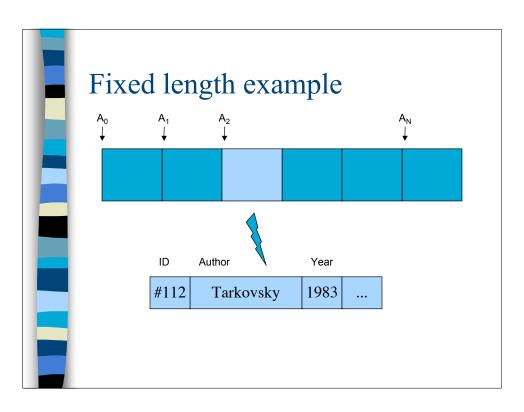
#### Document File

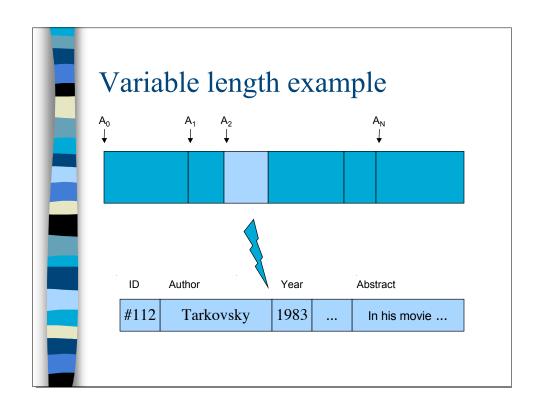
- A collection of documents is stored as a document file
- A representation of a document in a document file is called a record
- Type of document files
  - Sequential
  - Hashed
  - Hierarchical and netted

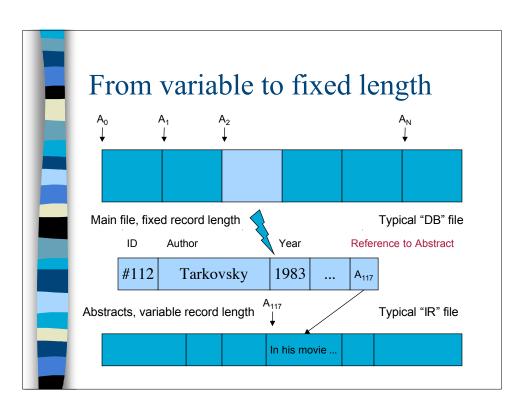
# Sequential files

- Documents are arranged in a sequence
  - Usually sorted by some criteria so similar documents are close to each other
- Records in a document file can have fixed of variable length
- Each record in a file has an address and can be retrieved given this address
  - Need random access device for efficiency







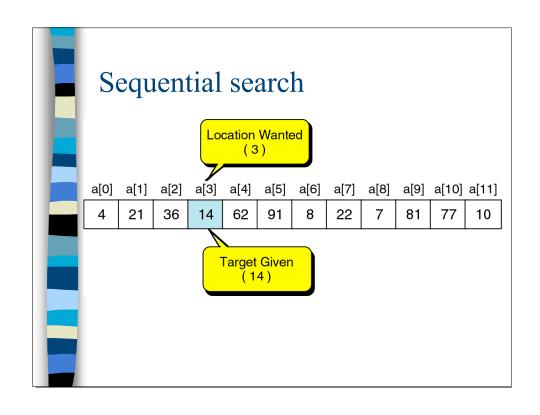


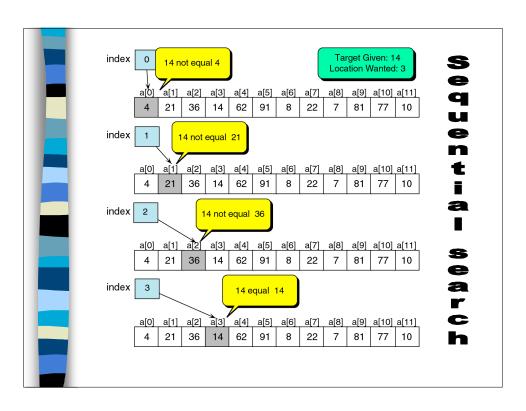
#### Main problem of search

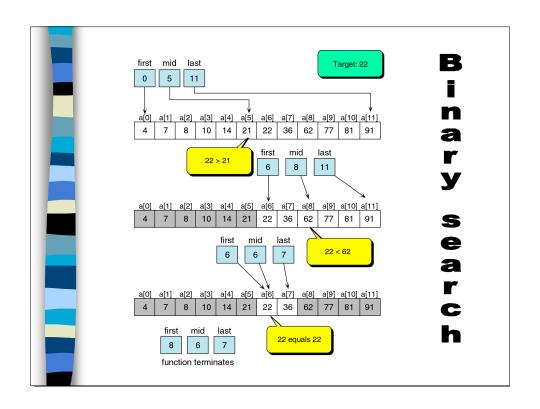
- Find all records (documents) with the given value of the key
  - Year = 1998
  - Fellini in Director
  - Brilliant in Abstract
- The search techniques for fixed and variable length record files are technically different but conceptually similar

## Search Techniques

- Sequential search, unordered records
  - Linked lists for variable size records
- Sequential search, ordered records
  - Linked lists for variable size records
- Binary search
  - Binary trees for variable size records
- Direct search (hashing)

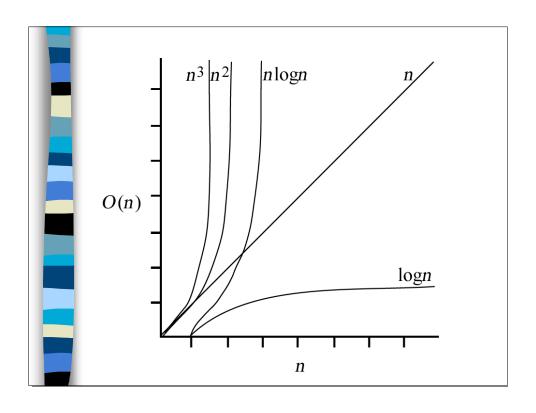


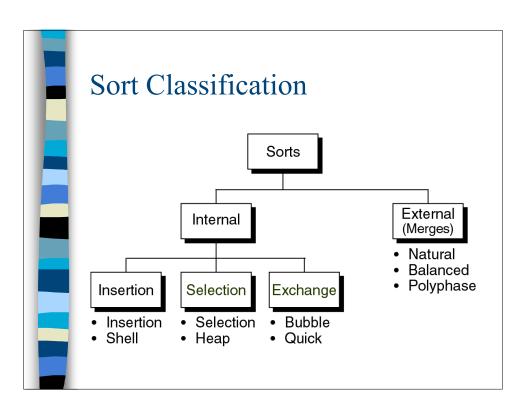




# Complexity

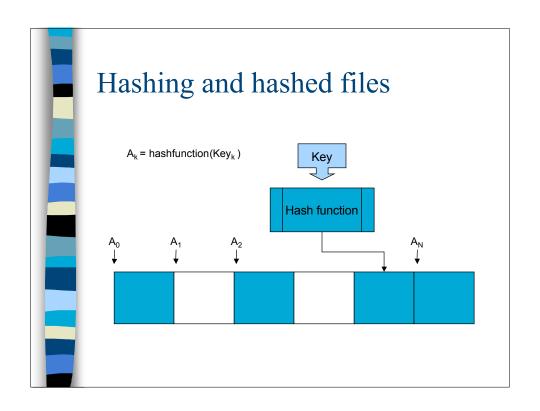
- Big-O notation
- Sequential search: n/2 (n if not found)
- Sequential ordered search: n/2 → O(n)
- Binary search → O(log<sub>2</sub> n)





# Complexity for various sorts

- Complexity for insertion sorts:
  - straight insertion: O(n<sup>2</sup>)
  - Shell sort O(n<sup>1.25</sup>)
- Complexity for selection sorts
  - straight selection: O(n<sup>2</sup>)
  - heap sort: O(nlog<sub>2</sub>n)
- Complexity for exchange sorts
  - bubble sort: O(n<sup>2</sup>)
  - quick sort: O(nlog<sub>2</sub>n)

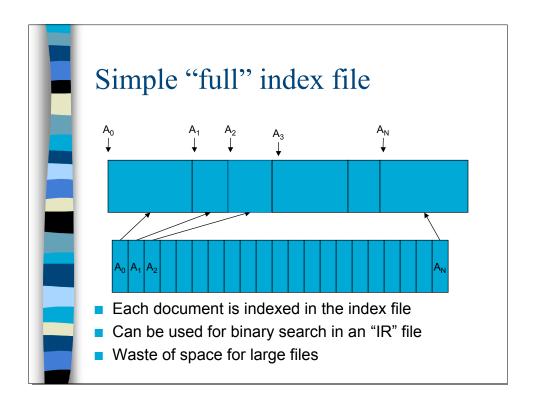


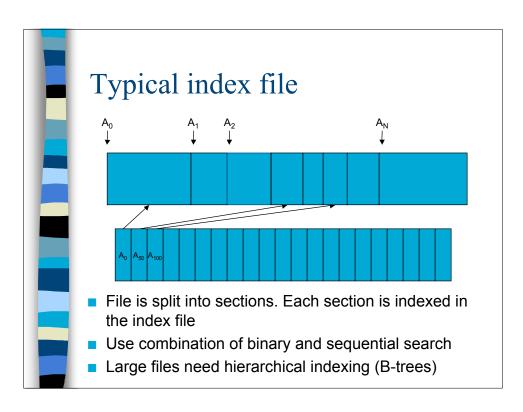
#### Problems of hashing

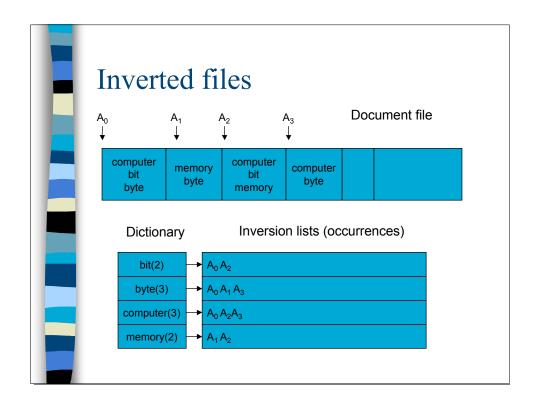
- Hard to define good hash function
  - Wasted space vs. collisions
- No sequential processing
- Similar documents are scattered all over the file
- As a result, hashing has relatively little use in IR

# Searching in IR document files

- Need additional data structures for fast search in large IR document files
  - Binary tree over sequential file
  - Indexed files
  - Inverted files
  - B-trees
  - Suffix trees
  - Signature files
  - Tries







#### What is in inversion lists?

- Document reference
  - Address, record number
- Location inside the document
  - Where is the word: address, number, block
- Parameters
  - Weight of this term for the document
- B-tree is better than dictionary to point to inversion lists

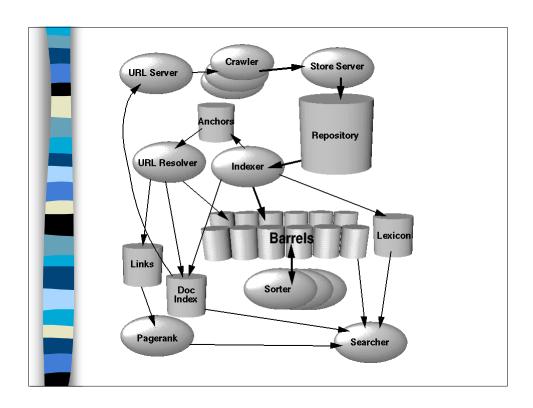
# Google

Not really searching the WWW, but querying an respresentation of a "pre-searched" WWW.

Google's indices map keys (search vocabulary elements) to web pages.

- Require ~ 50GB
- Proposal suggests that its Document Index is btree based (~10 GB)

The following image is from Brin and Page doc: http://www7.scu.edu.au/programme/fullpapers/1921/com1921.htm



#### Google, cont.

- The proposal of Sergey Brin and Lawrence Page estimated originally that they would need about 100 Million pages.
- Now over 1 Billion pages off by an order of magnitude.
- How big is a billion pages? 4 terabytes!

# Btree - requirements

- Invented by R. Bayer in 1970
- A Btree is a generalization of a Multiway tree which in turn is a generalization of a binary tree.
- Requirements:
  - Maintain balance
  - Minimize Disk I/O why?

#### Btree – requirements, cont.

- Disk access speed
  - between 3ms and 10ms
- Compare this to CPU speeds
- So, although btrees are old technology, they remain useful!
- Common to trees:

**RANDOM** access - not direct access

#### Btree - definition

- A multiway tree in which
  - All leaf nodes are on the same level
  - Every non-leaf node, except the root, has between M/2 and M descendents (leaf nodes have zero descendents)
  - The root can have 0 M descendents(All descendents are non-empty)
- **M** is the *order* of the btree
- What determines **M**?

#### **Btrees**

- The order of a binary tree is trivially 2.
- The *order* (**M**) of a btree is set at creation. A function of
  - Size of node How is this determined?
  - Size of keys (or partial keys)
- What does a node look like?

# Btree A simple example of Btree What is its order? 4 10 16 1 2 3 6 7 9 11 12 15 17 22 36

## Btree - height

- The maximum height of a btree index determines the path length or max number of accesses for a search. Remember, each node represents a potential disk access.
- Assume that each internal node has the minimum number of descendents (M/2); this results in maximum depth of tree.
- For **N** elements, max. height < log<sub>m/2</sub> ((N+1)/2)

So search is  $O(\log_{m/2} N)$ 

## Some max. height examples

■ For M = 200

$$\log_{M/2} (1M) <= 3$$

$$\log_{M/2} (1G) <= 5$$

$$\log_{M/2} (1T) <= 7$$

$$\log_{M/2} (1P) <= 8$$

$$\log_{M/2}$$
 (1E) <= 9

#### Btree Improvements

- Most Btrees today are really B+trees
  - Records (vs keys) are stored in leaf nodes
  - Leaf nodes are links to provide sequential as well as random access
- Can relax the constraint on number of elements for leaf nodes without affecting algorithms.
- Variable-length keys can relax bounds (m/2, m) for number of descendents
- High Concurrency multi-granular locking

#### Btree Access Methods

- Create a btree
- Destroy a btree
- Search for a specific record (query)
- Insert a record
- Delete a record
- Read a record
- Iterator operations
- Demo:
  - http://sky.fit.gut.edu.au/~maire/baobab/baobab.html
- Tutorial: http://www.bluerwhite.org/btree/